

International Centre for Radio Astronomy Research Calibration and direct validation of station embedded element patterns for SKA-Low prototype stations AAVS2 and EDA2

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Inyarrimanha Ilgari Bundara (operated by CSIRO)

Population Density: 0.002 km⁻²

Geraldton

Perth





Brief history of SKA-Low prototypes

- 2014: AAVS0.5 (Sutinjo et al.,2015)
 - 16 antennas analogue BF -> MWA
- 2016: EDA1 (Wayth et al., 2017)
 - 256 MWA antennas, hybrid beamformer
- 2017-2019: AAVS1 (Benthem et al. 2021)
 - 256 SKALA2 antennas
 - RFoF long distance signal transport
 - Full digital backend
 - Initial focus on basic functionality
 - Subsequent focus on calibration & stability



SKA-Low Prototypes – 2nd generation



SKA1-Low specs:

- 512 stations
- 256 antennas / station50-350 MHz
- Full digital beamforming
- 300 MHz instantaneous bandwidth
- Current prototypes:
 - EDA2
 - AAVS2
 - Called "Bridging Arrays"











Goals for the 2nd generation "bridging" arrays

- Calibration accuracy: can we calibrate the arrays to sufficient accuracy?
 - Evaluation of two antenna types with different electromagnetic mutual coupling and optimisations.
- Calibration stability: what is the timescale required for (re)calibration?
- On-sky sensitivity: measure it
- Exercise the firmware & software backends for monitor and control
- Understand the realities of deployment at scale on site

A significant change from the 1st generation system (AAVS1) moved the optical transmitters out of the antenna apex.



Inside a "SMART" box. 16 antennas electrical -> optical



Outputs: all-sky images, every 2 seconds



Science output: all-sky monitor with 2s timescale. Sokolowski et al., 2020.

Rate/strength of RFI sources in FM band: Tingay et al, 2020.



Results: sensitivity

- Snapshots are confusion limited, but difference images are noise-like
- This allows *direct measurement* of the on-sky array System Equivalent Flux Density (SEFD) from calibrated images

Consecutive snapshots separated by ~0.5s



5015 6011 7006







ICRAR

Aperture images – self holography





Outputs: All-sky map generated by EDA2 @ 160 MHz using the m-mode technique from 24hr drift scan





Results: calibration stability

Cal phase stddev: < 5 degs over 2 hours for EDA2. ~10 degs for AAVS2





Calibration (around midday) in all frequency channels every few days

Used to measure and correct antenna *delays*. Required for real-time beamforming.



Datasets, beamforming, sensitivity and monitoring

Monitoring the stability of delay solutions - AAVS2



Results: Verification of FEE patterns via solar calibration

- FEKO full EM simulations for AAVS2 and EDA2
- Probe beam by using sun as calibrator over ~6 hours, with 10min cal interval, when Gal Centre has set
- Provides a direct measure of each beam at each cal time





(There is one of these for all 256 antennas... too much to show.)

ICRAR

Stddev over time for each antenna – **AAVS2** 110 MHz

- Apply FEE model to data. A perfect model would result in zero phase.
- Residual phase variation over time is 5-7 degs after applying FEE beam correction
- This is **direct validation of FEE models from an astronomical source**. Residuals are from many possibilities, but at an acceptable level.



Predicting beamforming errors from FEE models

 Station beamforming is performed using geometric corrections only, differences in phase/amp between station antennas turn into beamforming errors

CRA

- We can use the same FEE models to predict the level of beamforming errors, as a function of frequency, *assuming ideal calibration*
- We take 3 representative 6-hour tracks on sources at 0, -30 and -60 degs DEC.











Summary

Macario et al., 2021. SPIE JATIS. (for AAVS2) Wayth et al., 2021. SPIE JATIS. (for EDA2) Sokolowski et al, 2020.

2020, van Es et al.

- AAVS2 and EDA2 running since mid 2019
- Calibration phase stability shown to be stable over months
- Sensitivity measured at 5 reference frequencies
- Arrays being used for all-sky and transient science
- Direct verification of FEE beam models using astronomical source
- Predicted beamforming errors (sensitivity loss) due to coupling over large freq range



Stddev over time for each antenna – EDA2 230 MHz

Intrinsic phase variation over time is 4-7 degs (at this freq). Corrections make negligible difference.







Calibration approaches

Dominant compact source (sun)

Better at higher freqs. No good <~ 100 MHz

Delay calibration

- Fit linear phase ramp vs freq for each pol. -> delay
- Successfully doing this since AAVS1

All-sky model: Average Element Pattern

- Use rescaled Haslam and beam model including the Sun
- Successfully doing this since AAVS1

All-sky model: Full element patterns

• Done in simulations, looking at applying to AAVS2 now

Results: stability of delay solutions - EDA2





SKALA4 YY vs XX at large zenith angle (160 MHz)





Status

Dominant compact source (sun)

- Better at higher freqs. No good <~ 100 MHz
- During March-April timeframe, gives unambiguous data

Delay calibration

- Fit linear phase ramp vs freq for each pol. -> delay
- Successfully doing this since AAVS1

All-sky model: Average Element Pattern

- Use rescaled Haslam and beam model including the Sun
- Successfully doing this since AAVS1

All-sky model: Full element patterns

- Done in simulations, looking at applying to AAVS2 now
- Still combines the imperfect sky model with beam model. Hard to deconvolve.